021500-43

证　明

CERTIFICATE

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国际申请号：　　**PCT/CN03/00048**

INTERNATIONAL APPLICATION NUMBER

国际申请日：　　20 JAN 2003 (20.01.2003)

INTERNATILNAL FILING DATE

发明名称：　　**System and Method for Manufacture of a Hard Disc Drive Arm and Bonding of Magnetic Head to Suspension on a Drive Arm**

TITLE OF INVENTION

申请人：　　**SAE MAGNETICS(H.K.)LTD**

APPLICANT

中华人民共和国国家知识产权局局长

COMMISSIONER OF THE STATE INTELLECTUAL PROPERTY OFFECE OF THE PEOPLE'S REPUBLIC OF CHINA

王景川

二零零三年二月二十八日

FEBRUARY. 28. 2003

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REQUEST

The undersigned requests that the present international application be processed according to the Patent Cooperation Treaty.

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International Application No. PCT/CN 03/00048

International Filing Date 20 JAN 2003 (20.01.03)

RO/CN 中华人民共和国国家知识产权局 PCT International Application

Name of receiving Office and "PCT International Application"

Applicant's or agent's file reference *(if desired) (12 characters maximum)* FPEL02150043

Box No. I TITLE OF INVENTION

System and Method for Manufacture of a Hard Disc Drive Arm and Bonding of Magnetic Head to Suspension on a Drive Arm

Box No. II APPLICANT ☐ This person is also inventor

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Box No. IV AGENT OR COMMON REPRESENTATIVE; OR ADDRESS FOR CORRESPONDENCE

The person identified below is hereby/has been appointed to act on behalf of the applicant(s) before the competent International Authorities as: ☒ agent ☐ common representative

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- ☒ inventor only *(If this check-box is marked, do not fill in below.)*

Applicant's registration No. with the Office

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This person is applicant for the purposes of: ☐ all designated States ☐ all designated States except the United States of America ☐ the United States of America only ☐ the States indicated in the Supplemental Box

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This person is applicant for the purposes of: ☐ all designated States ☐ all designated States except the United States of America ☐ the United States of America only ☐ the States indicated in the Supplemental Box

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This person is:
- ☐ applicant only
- ☐ applicant and inventor
- ☐ inventor only *(If this check-box is marked, do not fill in below.)*

Applicant's registration No. with the Office

State *(that is, country)* of nationality:

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This person is:
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Box No. V DESIGNATION OF STATES *Mark the applicable check-boxes below; at least one must be marked.*

The following designations are hereby made under Rule 4.9(a):

Regional Patent

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☐ **AU** Australia	☐ **IN** India	☐ **RO** Romania
☐ **AZ** Azerbaijan	☐ **IS** Iceland	☐ **RU** Russian Federation
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☐ **BZ** Belize	☐ **KR** Republic of Korea	☐ **SK** Slovakia
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Box No. VI PRIORITY CLAIM

The priority of the following earlier application(s) is hereby claimed:

Filing date of earlier application *(day/month/year)*	Number of earlier application	Where earlier application is:		
		national application: country or Member of WTO	regional application:* regional Office	international application: receiving Office
item (1)				
item (2)				
item (3)				
item (4)				
item (5)				

☐ Further priority claims are indicated in the Supplemental Box.

The receiving Office is requested to prepare and transmit to the International Bureau a certified copy of the earlier application(s) *(only if the earlier application was filed with the Office which for the purposes of this international application is the receiving Office)* identified above as:

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** Where the earlier application is an ARIPO application, indicate at least one country party to the Paris Convention for the Protection of Industrial Property or one Member of the World Trade Organization for which that earlier application was filed (Rule 4.10(b)(ii)):* . . . .

. . . . . .

Box No. VII INTERNATIONAL SEARCHING AUTHORITY

Choice of International Searching Authority (ISA) *(if two or more International Searching Authorities are competent to carry out the international search, indicate the Authority chosen; the two-letter code may be used)*:

ISA / . . . . . .

Request to use results of earlier search; reference to that search *(if an earlier search has been carried out by or requested from the International Searching Authority):*

Date *(day/month/year)* Number Country *(or regional Office)*

Box No. VIII DECLARATIONS

The following **declarations** are contained in Boxes Nos. VIII (i) to (v) *(mark the applicable check-boxes below and indicate in the right column the number of each type of declaration)*: Number of declarations

☐ Box No. VIII (i)	Declaration as to the identity of the inventor	:
☐ Box No. VIII (ii)	Declaration as to the applicant's entitlement, as at the international filing date, to apply for and be granted a patent	:
☐ Box No. VIII (iii)	Declaration as to the applicant's entitlement, as at the international filing date, to claim the priority of the earlier application	:
☐ Box No. VIII (iv)	Declaration of inventorship (only for the purposes of the designation of the United States of America)	:
☐ Box No. VIII (v)	Declaration as to non-prejudicial disclosures or exceptions to lack of novelty	:

Box No. IX CHECK LIST; LANGUAGE OF FILING

This international application **contains:**

(a) the following number of **sheets in paper form:**

request (including declaration sheets)	:	5
description (excluding sequence listing part)	:	5
claims	:	4
abstract	:	1
drawings	:	8
Sub-total number of sheets	:	23
sequence listing part of description *(actual number of sheets if filed in paper form, whether or not also filed in computer readable form; see (b) below)*	:	
Total number of sheets	:	23

(b) sequence listing part of description filed in **computer readable form**

(i) ☐ only (under Section 801(a)(i))

(ii) ☐ in addition to being filed in paper form (under Section 801(a)(ii))

Type and number of carriers (diskette, CD-ROM, CD-R or other) on which the sequence listing part is contained *(additional copies to be indicated under item 9(ii), in right column)*: .....

This international application is **accompanied by** the following item(s) *(mark the applicable check-boxes below and indicate in right column the number of each item):*

		Number of items
1. ☒ fee calculation sheet	:	1
2. ☒ original separate power of attorney	:	1
3. ☐ original general power of attorney	:	
4. ☐ copy of general power of attorney; reference number, if any:	:	
5. ☐ statement explaining lack of signature	:	
6. ☐ priority document(s) identified in Box No. VI as item(s):	:	
7. ☐ translation of international application into *(language)*:	:	
8. ☐ separate indications concerning deposited microorganism or other biological material	:	
9. ☐ sequence listing in computer readable form (indicate also type and number of carriers (diskette, CD-ROM, CD-R or other))		
(i) ☐ copy submitted for the purposes of international search under Rule 13*ter* only (and not as part of the international application)	:	
(ii) ☐ *(only where check-box (b)(i) or (b)(ii) is marked in left column)* additional copies including, where applicable, the copy for the purposes of international search under Rule 13*ter*	:	
(iii) ☐ together with relevant statement as to the identity of the copy or copies with the sequence listing part mentioned in left column	:	
10. ☐ other *(specify)*:	:	

Figure of the drawings which should accompany the abstract: Fig 3a

Language of filing of the international application: EN

Box No. X SIGNATURE OF APPLICANT, AGENT OR COMMON REPRESENTATIVE

Next to each signature, indicate the name of the person signing and the capacity in which the person signs (if such capacity is not obvious from reading the request).

CHINA PATENT AGENT (HONG KONG) LIMITED 中國專利代理(香港)有限公司 專利申請專用章

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1. Date of actual receipt of the purported international application: 20 JAN 2003 (20.01.03)

2. Drawings: ☐ received: ☐ not received:

3. Corrected date of actual receipt due to later but timely received papers or drawings completing the purported international application:

4. Date of timely receipt of the required corrections under PCT Article 11(2):

5. International Searching Authority (if two or more are competent): ISA /

6. ☐ Transmittal of search copy delayed until search fee is paid

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FEE CALCULATION SHEET
Annex to the Request

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International Application No. PCT/CN03/00048

Date stamp of the receiving Office: 20 JAN 2003 (20.01.03)

Applicant's or agent's file reference: FPEL02150043

Applicant: SAE MAGNETICS (H.K.) LTD.

CALCULATION OF PRESCRIBED FEES

1. TRANSMITTAL FEE	CNY500	T	CNY500.-
2. SEARCH FEE	CNY1500	S	CNY1500.-

International search to be carried out by: CN
(If two or more International Searching Authorities are competent to carry out the international search, indicate the name of the Authority which is chosen to carry out the international search.)

3. INTERNATIONAL FEE

Basic Fee

Where item (b) of Box No. IX applies, enter **Sub-total number of sheets**
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b1 first 30 sheets	CHF650	b1	CHF650.-
b2 ____ (number of sheets in excess of 30) x ____ (fee per sheet) =		b2	
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1 (number of designation fees payable *(maximum 5)*)	x	CHF140 (amount of designation fee)	=	CHF140 D	CHF140.-
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4. FEE FOR PRIORITY DOCUMENT *(if applicable)*		P	
5. TOTAL FEES PAYABLE Add amounts entered at T, S, I and P, and enter total in the TOTAL box	CNY2000CHF790 TOTAL		CNY2000.- CHF790.-

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CHINA PATENT (HONG KONG) LIMITED 中國專利(香港)有限公司 專用章

SYSTEM AND METHOD FOR MANUFACTURE OF A HARD DISK DRIVE ARM AND BONDING OF MAGNETIC HEAD TO SUSPENSION ON A DRIVE ARM

Background Information

The present invention relates to magnetic hard disk drives. More specifically, the invention relates to a system for manufacturing a hard disk drive arm and the bonding of magnetic head to suspension on the drive arm.

Among the better known data storage devices are magnetic disk drives of the type in which a magnetic head slider assembly floats on an air bearing at the surface of a rotating magnetic disk. Such disk drives are often called 'Winchester'-type drives. In these, one or more rigid magnetic disks are located within a sealed chamber together with one or more magnetic head slider assemblies. The magnetic disk drive may include one or more rigid magnetic disks, and the slider assemblies may be positioned at one or both sides of the magnetic disks.

Figure 1 provides an illustration of a typical hard drive as used in the art. The slider assembly 108 may be mounted in a manner which permits gimbaled movement at the free outer end of the arm 102 such that an air bearing between the slider assembly 108 and the surface of the magnetic disk 104 can be established and maintained. The drive arm 102 is coupled to an appropriate mechanism, such as a voice-coil motor (VCM) 106, for moving the arm 102 across the surface of the disk 104 so that a magnetic head contained within the slider assembly 108 can address specific concentric data tracks on the disk 104 for writing information onto or reading information from the data tracks.

Figure 2 provides an illustration of a hard drive arm and magnetic head as used in the art. Typically, the magnetic head (slider) 202 is electrically connected to the head gimbal assembly (HGA) by bonding means, such as gold ball bonding (GBB), solder bump bonding (SBB), and ultrasonic welding. Typically, four

connection points (balls) 204 are provided to electrically connect the magnetic head 202 to the suspension tongue/head gimbal assembly (HGA) 206. Two of the balls 204 are for the 'read' operation, and two of the balls 204 are for the 'write' operation. To prevent the bonding balls 204 from hardening with the magnetic head 202 in an undesirable orientation, a fixture 208 is used to strongly clamp the suspension tongue 206 and head 202 to be physically stable for ball 204 application by a soldering tool 210, etc. A base support 211 and a first clamping cover 220 stabilize the magnetic head 202. A second clamping cover 221 stabilizes the suspension tongue 206. A second base support (not shown) secures the load beam 212.This fixture 208 is utilized to prevent a change in orientation of the head 202 by the force of the soldering tool 210 during application.However, the clamping force of the fixture 208 is often enough to deform the magnetic head 202 and suspension tongue 212 structure causing improper orientation(alignment).Further, the forces involved have a tendency to damage the head 202 surface as well as the head suspension dimple 214.

It is therefore desirable to have a system to enable magnetic head electrical bonding while avoiding the aforementioned problems, in addition to providing other advantages.

In an aspect of the present invention, a system for manufacturing a data storage device comprising: a placement device to physically stabilize a hard drive head device for electrical bonding of said head device to a hard drive arm component, wherein said placement device utilizes sub-ambient pressure to maintain the position of said head device with respect to said arm component for said electrical bonding.

In a further aspect of the present invention, a method for manufacturing a data storage device comprising:

physically stabilizing, by a placement device, a hard drive head device for electrical bonding of said head device to a hard drive arm component and

utilizing, by said placement device, sub-ambient pressure to maintain the

position of said head device with respect to said arm component for said electrical bonding.

Brief Description Of The Drawings

Figure 1 provides an illustration of a typical hard drive as used in the art.

Figure 2 provides an illustration of a hard drive arm and magnetic head as used in the art.

Figure 3 illustrates a hard drive arm suspension, magnetic head, and head placement device according to an embodiment of the present invention.

Figure 4 illustrates placement device design according to two different embodiments of the present invention.

Figure 5 illustrates placement device design according to three additional embodiments of the present invention.

Figure 6 illustrates placement device design according to three further embodiments of the present invention.

Figure 7 illustrates placement device design for 'U'-shaped micro-actuator accommodation according to an embodiment of the present invention.

Figure 8 illustrates the design of a simultaneous operation placement device according to an embodiment of the present invention.

Detailed Description

Figure 3 illustrates a hard drive arm suspension, magnetic head, and head placement device according to an embodiment of the present invention.As shown in figure 3a, in one embodiment, the placement device 305 has two vacuum tubes 301,304.The first vacuum pipe (tube) 301 has a fixture 311 that mates to the magnetic head 321 of a hard drive.As shown in figure 3b, in this embodiment, the first vacuum tube fixture 311 has a stepped 313 surface that mates with the head 321 in such a way that prevents rotational motion of the head 321 with respect to the placement device 305 (and thus, the suspension tongue 322).In one

embodiment, the step 313 is between 100 micrometers and 280 micrometers.In one embodiment, the second vacuum tube has a fixture mate-able to the load beam 324.Further, an alignment pin 303 is provided that is capable of being inserted into the tooling hole of the load beam 324 for ensuring proper alignment.In this embodiment, the placement device is secured to the magnetic head 321 and load beam 324 by sub-ambient pressure imposed by the first 301 and second 302 vacuum tubes, the first vacuum tube 301 applying suction force to the air bearing surface (ABS) of the slider/head 321 and the second vacuum tube 302 applying suction force to the load beam 324.

Figure 4 illustrates placement device design according to two different embodiments of the present invention.In one embodiment, shown in figure 4a and 4b, the fixture 402 of the first vacuum tube has an integrated step 403 to prevent rotational (yaw) 406 and longitudinal 408 motion of the magnetic head 404 during bonding ball 410 application. In another embodiment, shown in figure 4c and 4d, the fixture 412 of the first vacuum tube has an externally-mounted step structure 413.Further, figures 4b and 4d illustrate the air inlets of the first and second vacuum tubes.

Figure 5 illustrates placement device design according to three additional embodiments of the present invention.As shown in figure 5b, in one embodiment, an externally-mounted step structure 501 is provided with a side protrusion 502 to prevent transverse 503 motion (as well as longitudinal 504 and rotational 505 motion) of the magnetic head 508 (See figure 5a).As shown in figure 5c, in another embodiment, an externally-mounted step structure 511 is provided with two side protrusions 512 to prevent transverse 513 motion (as well as longitudinal 514 and rotational 515 motion) of the magnetic head 508 (See figure 5a). As shown in figure 5d, in yet another embodiment, an externally-mounted step structure 521 is provided with two side protrusions 522.Further, in this embodiment, a notch 524 is provided in the step 521 to allow for arm component clearance.

Figure 6 illustrates placement device design according to three further embodiments of the present invention.As shown in figure 6b, in one embodiment, the first vacuum tube 602 has an 'L'-shaped step structure 601 integrated in its mating surface to prevent transverse 603 motion (as well as longitudinal 604 and rotational 605 motion) of the magnetic head 608 (See figure 6a).As shown in figure 6c, in another embodiment, the first vacuum tube 612 has a 'U'-shaped step structure 611 integrated in its mating surface.As shown in figure 6d, in yet another embodiment, the first vacuum tube 622 has a 'U'-shaped step structure 621 integrated in its mating surface with a notch 623 provided to allow for arm component clearance.

Figure 7 illustrates placement device design for 'U'-shaped micro-actuator accommodation according to an embodiment of the present invention.As shown in figures 7b, 7c, and 7d, in one embodiment, a first vacuum tube 702 has an externally-mounted step 704 and two side-mounted steps 706 to restrict the motion of a magnetic head 708 that is mounted in a micro-actuator, such as a 'U'-shaped micro-actuator 710.This embodiment accommodates the shape of such a micro-actuator 710 while preventing the motion of the head 708 and micro-actuator 710 during the bonding process.

Figure 8 illustrates the design of a simultaneous operation placement device according to an embodiment of the present invention.In one embodiment, multiple individual placement devices 802 are combined into one machine 804 in order to stabilize components of many hard drive load arms for simultaneous head bonding operations.

Although several embodiments are specifically illustrated and described herein, it will be appreciated that modifications and variations of the present invention are covered by the above teachings and within the purview of the appended claims without departing from the spirit and intended scope of the invention.

What is claimed is

1.A system for manufacturing a data storage device comprising:
a placement device to physically stabilize a hard drive head device for electrical bonding of said head device to a hard drive arm component, wherein said placement device utilizes sub-ambient pressure to maintain the position of said head device with respect to said arm component for said electrical bonding.

2.The system of claim 1, wherein said hard drive head device is a hard disk drive magnetic head.

3.The system of claim 2, wherein said hard drive arm component is a suspension tongue.

4.The system of claim 1, wherein said electrical bonding is ball bonding.

5.The system of claim 4, kwherein said electrical bonding is a type selected from the group consisting of gold ball bonding (GBB), solder bump bonding (SBB), ultrasonic welding, and stitch bonding.

6.The system of claim 1, wherein said placement device includes a first vacuum tube structure for providing said sub-ambient pressure to affix said first vacuum tube structure to said head device.

7.The system of claim 6, further comprising an alignment pin protruding from said placement device.

8.The system of claim 7, wherein said alignment pin is capable of being inserted into a suspension tooling hole for ensuring said proper alignment.

9.The system of claim 7, further comprising a second vacuum tube structure for providing sub-ambient pressure, wherein said first vacuum tube structure vacuum-couples to said head device and said second vacuum tube structure vacuum-couples to a suspension load beam attached to said arm component.

10.The system of claim 9, wherein the first vacuum tube structure includes a step structure mate-able to an edge of the head device.

11.The system of claim 10, wherein said step structure is mate-able to one or more edges of said head device.

12.The system of claim 11, wherein said step structure is an integral structure of the first vacuum tube.

13.The system of claim 11, wherein said step structure is an external structure.

14.The system of claim 9, wherein said first vacuum tube structure is a material selected from the group consisting of Stainless Steel, Copper, Aluminum Oxide, Polyimide, and Ceramic.

15.The system of claim 9, wherein said second vacuum tube structure is a material selected from the group consisting of Stainless Steel, Copper, Aluminum Oxide, Polyimide, and Ceramic.

16.A method for manufacturing a data storage device comprising:
physically stabilizing, by a placement device, a hard drive head device for electrical bonding of said head device to a hard drive arm component and
utilizing, by said placement device, sub-ambient pressure to maintain the

position of said head device with respect to said arm component for said electrical bonding.

17.The method of claim 16, wherein said hard drive head device is a hard disk drive magnetic head.

18.The method of claim 17, wherein said hard drive arm component is a suspension tongue.

19.The method of claim 16, wherein said electrical bonding is ball bonding.

20.The method of claim 19, wherein said electrical bonding is a type selected from the group consisting of gold ball bonding (GBB), solder bump bonding (SBB), ultrasonic welding, and stitch bonding.

21.The method of claim 16, wherein said placement device includes a first vacuum tube structure for providing said sub-ambient pressure to affix said first vacuum tube structure to said head device.

22.The method of claim 21, further comprising:
providing an alignment pin protruding from said placement device.

23.The method of claim 22, wherein said alignment pin is capable of being inserted into a suspension tooling hole for ensuring said proper alignment.

24.The method of claim 22, further comprising:
providing sub-ambient pressure, by a second vacuum tube;
vacuum-coupling said first vacuum tube structure to said head device; and
vacuum-coupling said second vacuum tube structure to a suspension load beam

attached to said arm component.

25.The method of claim 24, wherein the first vacuum tube structure includes a step structure mate-able to an edge of the head device.

26.The method of claim 25, wherein said step structure is mate-able to at least the leading edge of said head device.

27.The method of claim 24, wherein said first vacuum tube structure is a material selected from the group consisting of Stainless Steel, Copper, Aluminum Oxide, Polyimide, and Ceramic.

28.The method of claim 24, wherein said second vacuum tube structure is a material selected from the group consisting of Stainless Steel, Copper, Aluminum Oxide, Polyimide, and Ceramic.

Abstract

A system and method are disclosed for the manufacture of a hard disk drive arm and the bonding of magnetic head to suspension on the drive arm.

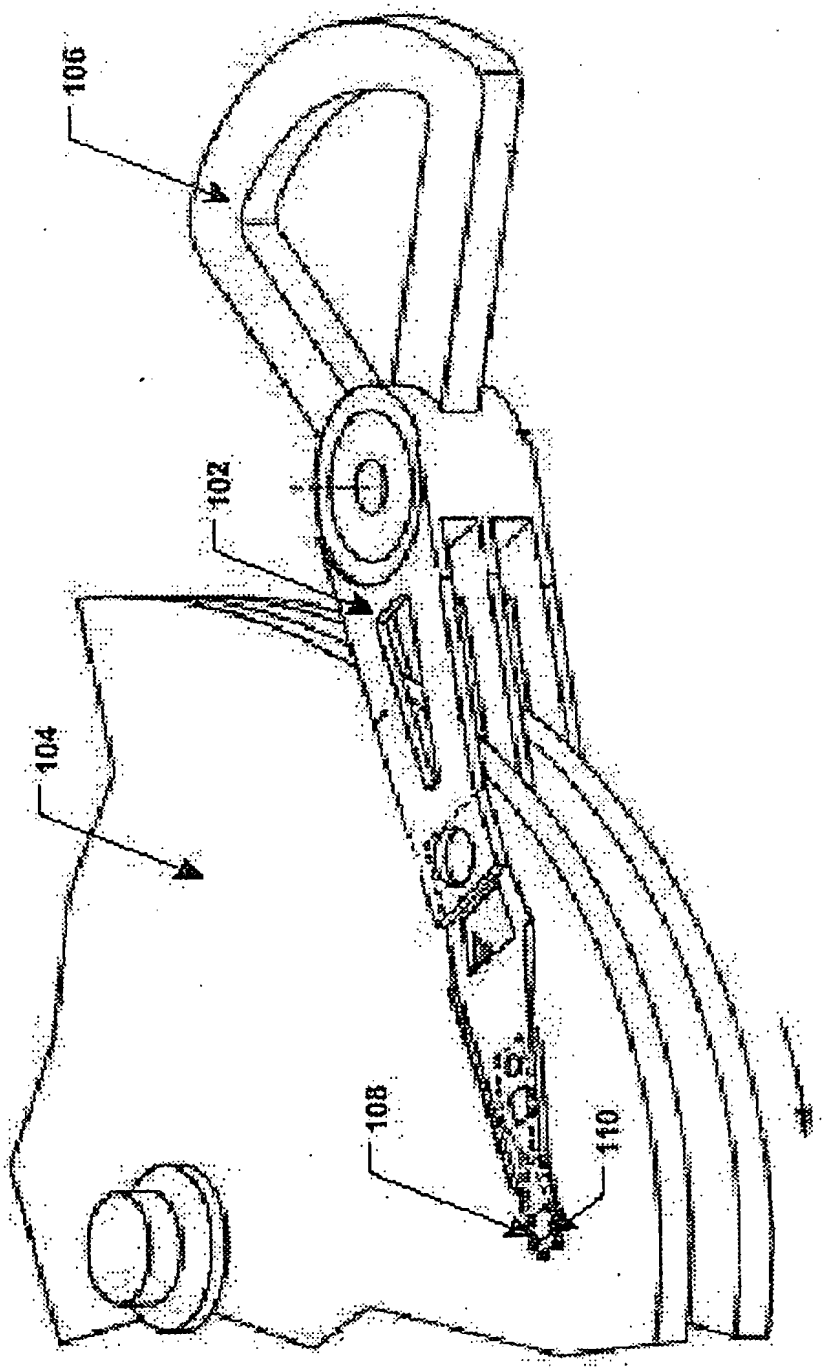

FIG. 1
(Prior Art)

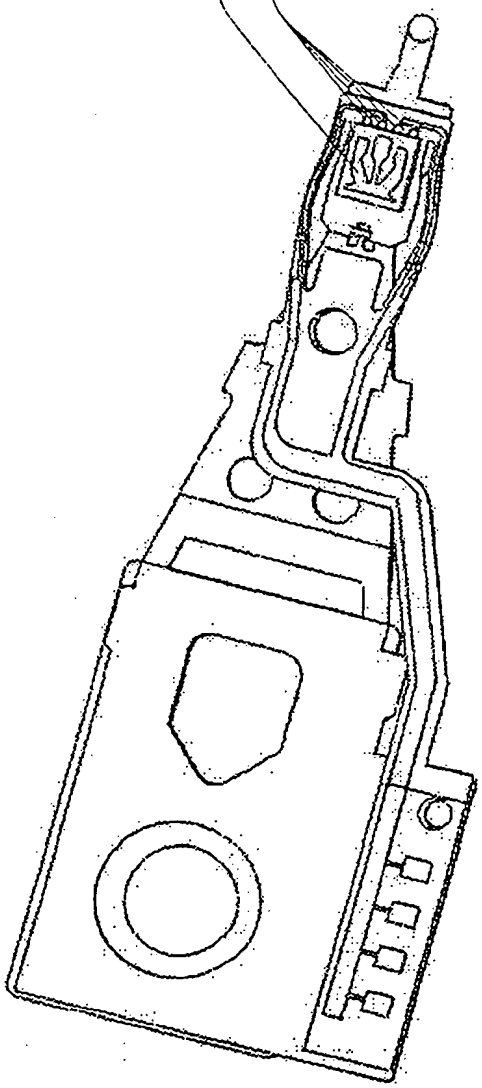

FIG. 2a

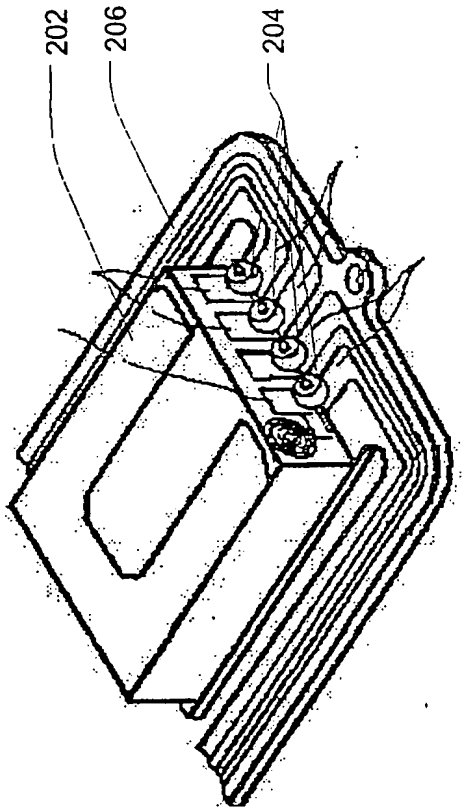

FIG. 2b

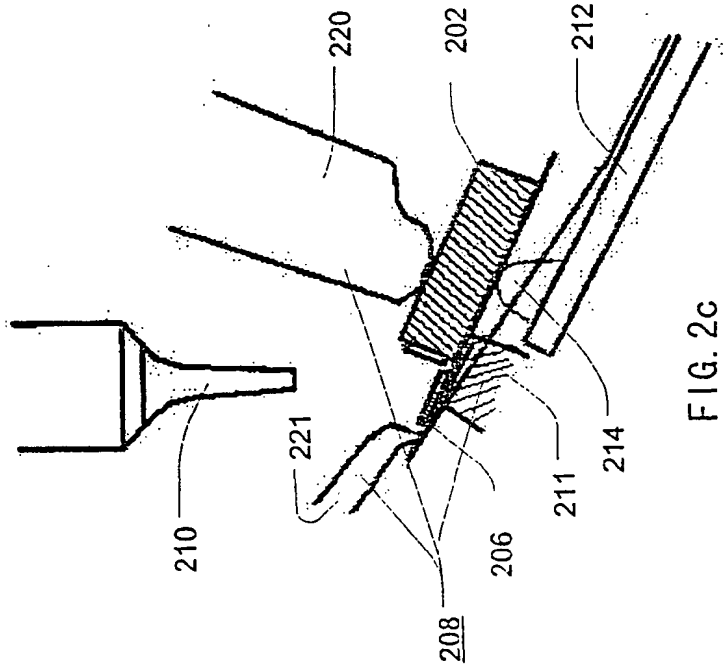

FIG. 2c

FIG. 2
(Prior Art)

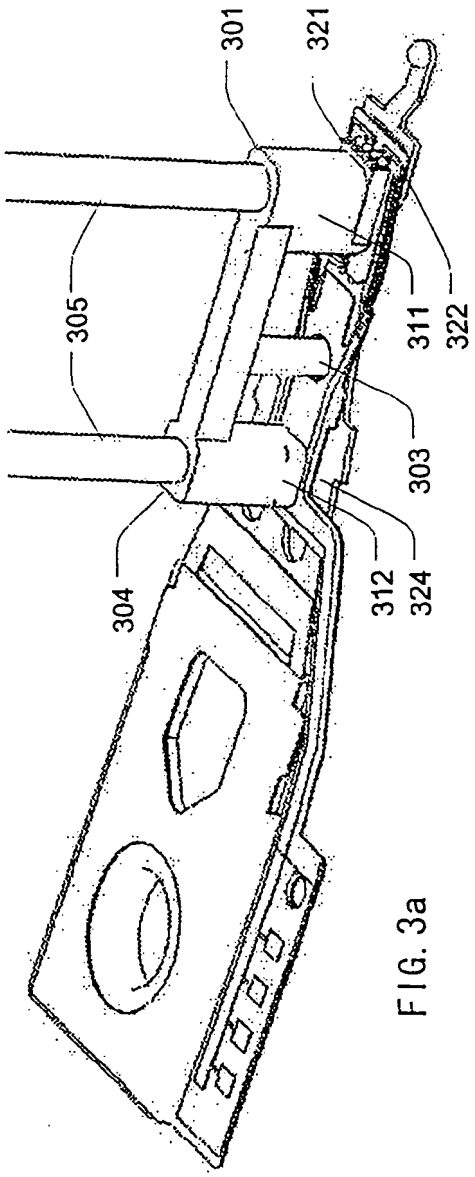

FIG. 3a

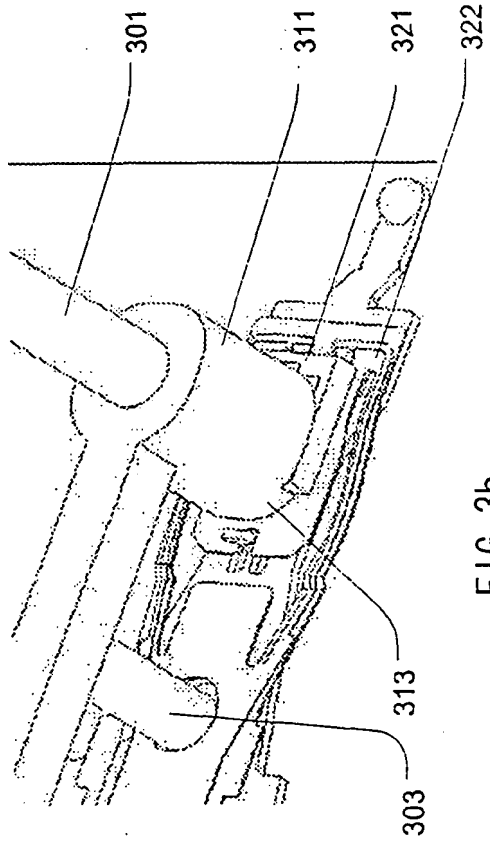

FIG. 3b

FIG. 3

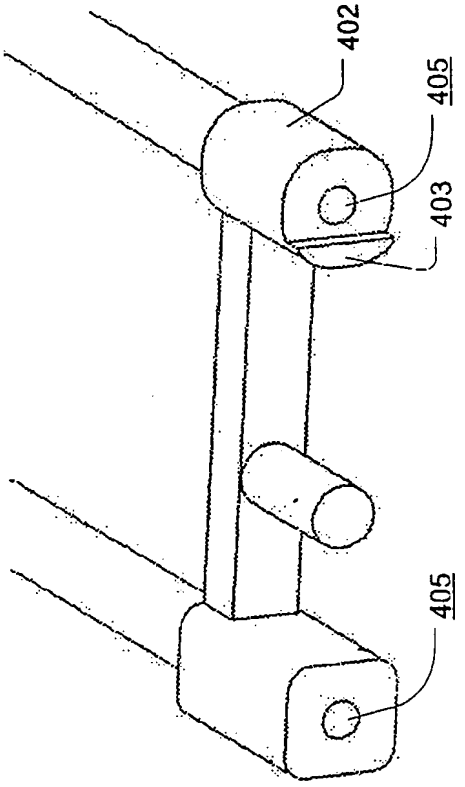

FIG. 4b

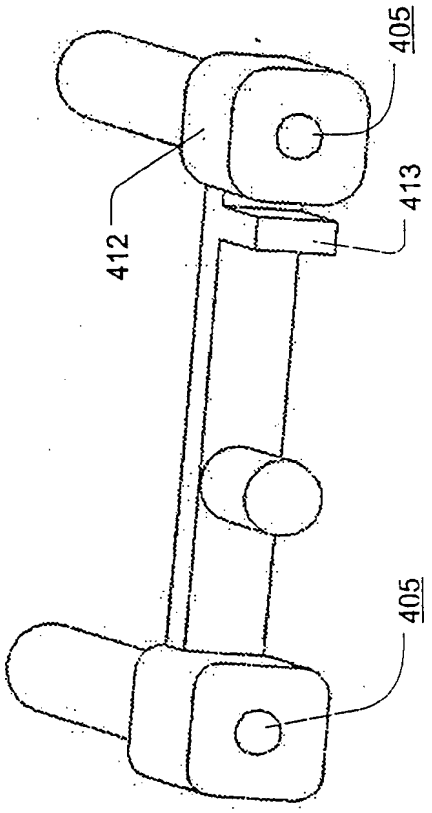

FIG. 4d

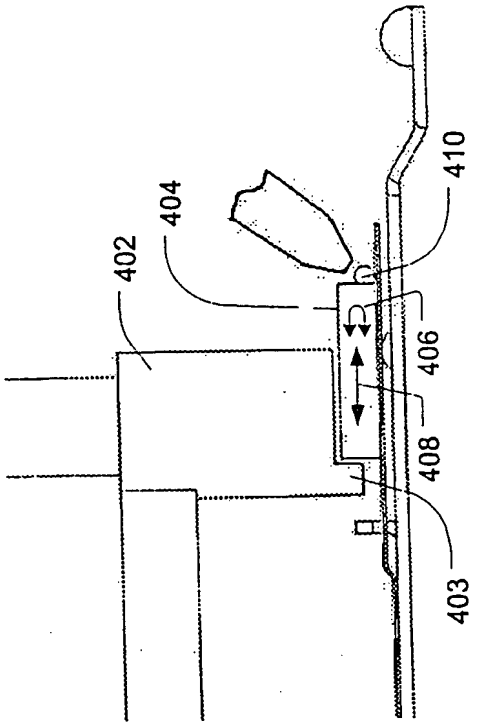

FIG. 4a

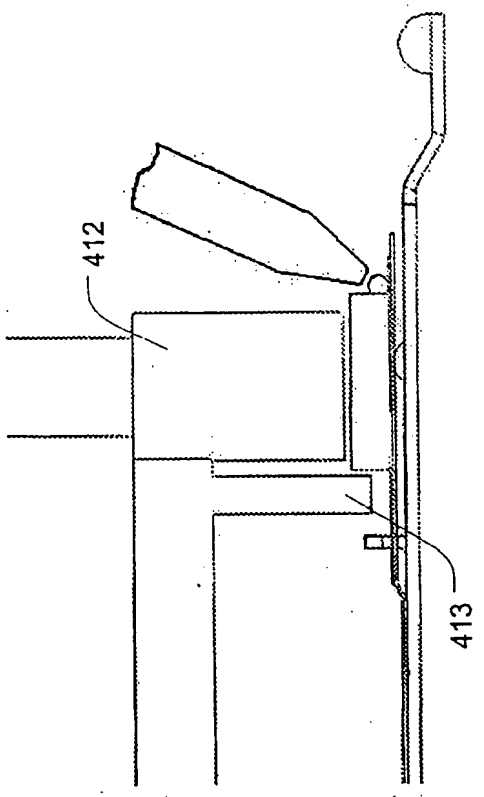

FIG. 4c

FIG. 4

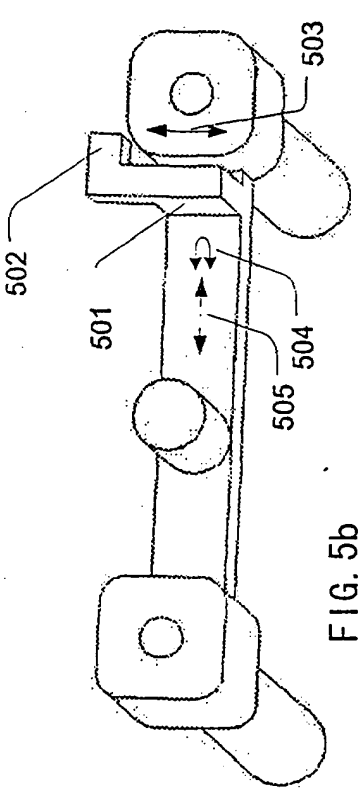

FIG. 5b

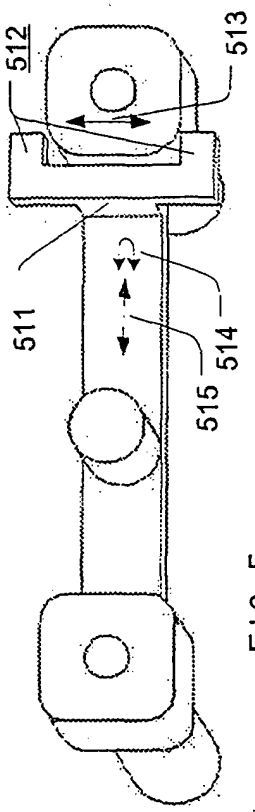

FIG. 5c

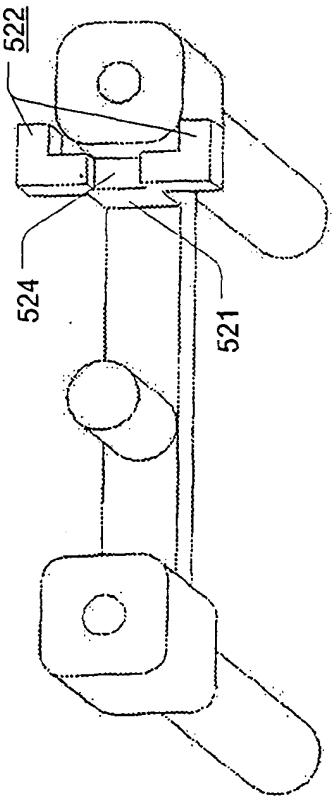

FIG. 5d

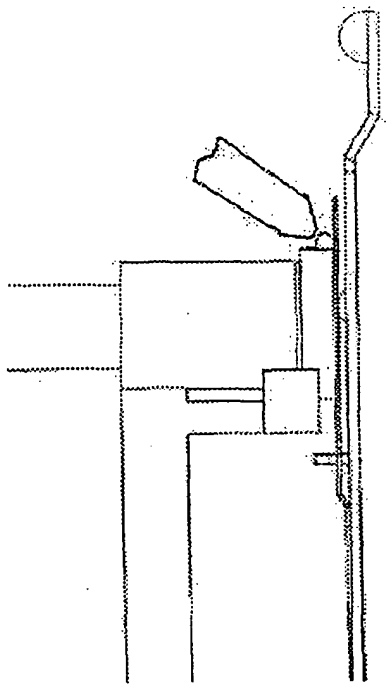

FIG. 5a

FIG. 5

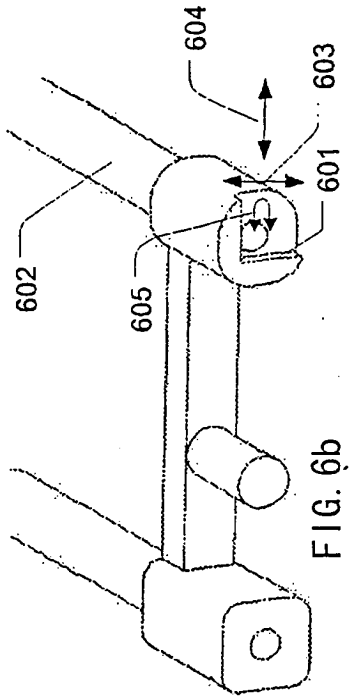

FIG. 6b

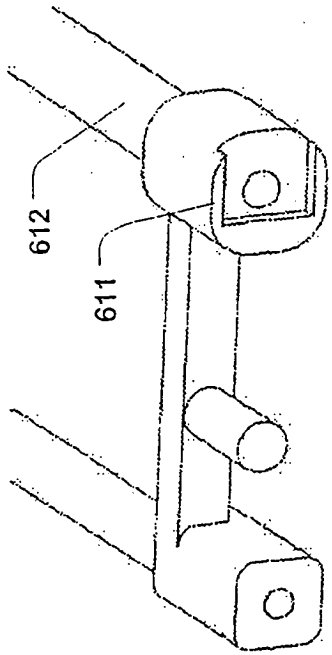

FIG. 6c

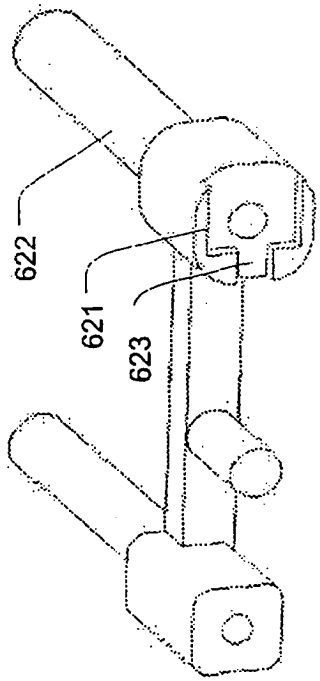

FIG. 6d

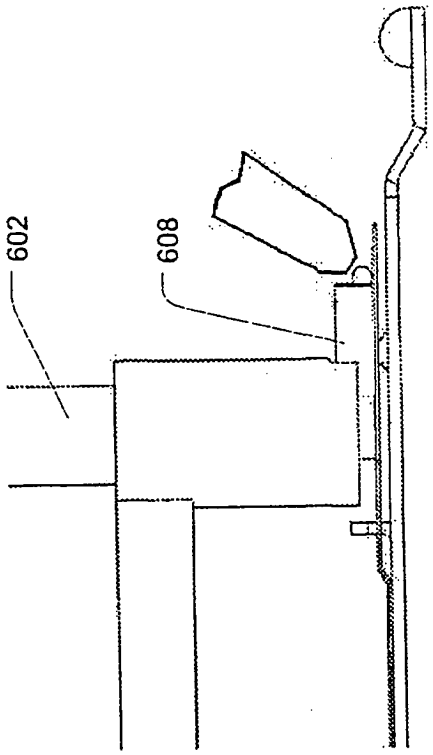

FIG. 6a

FIG. 6

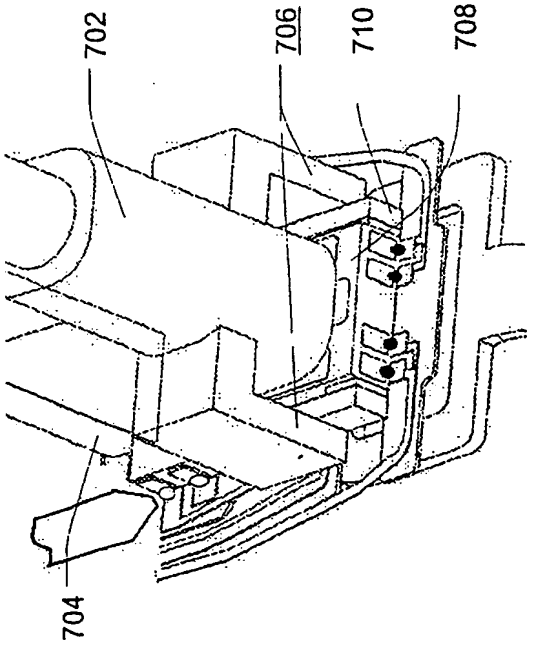

FIG. 7b

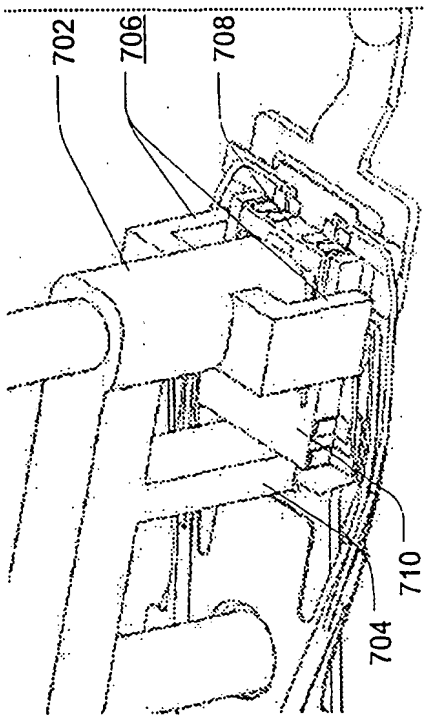

FIG. 7c

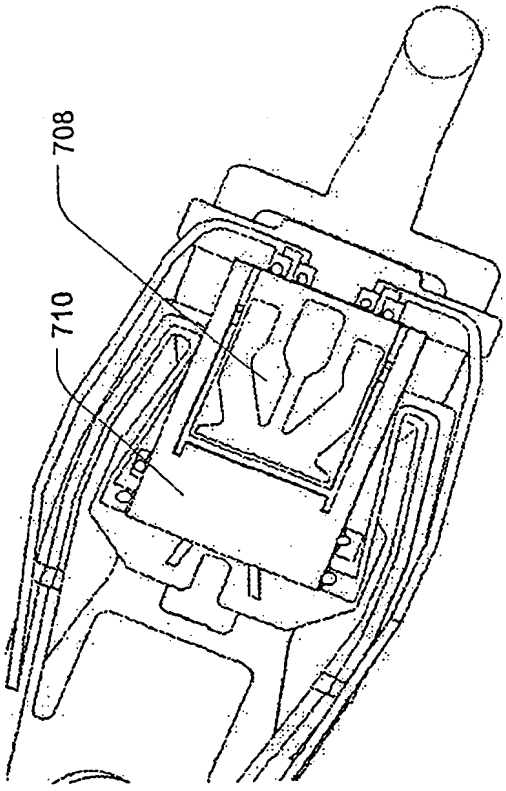

FIG. 7a

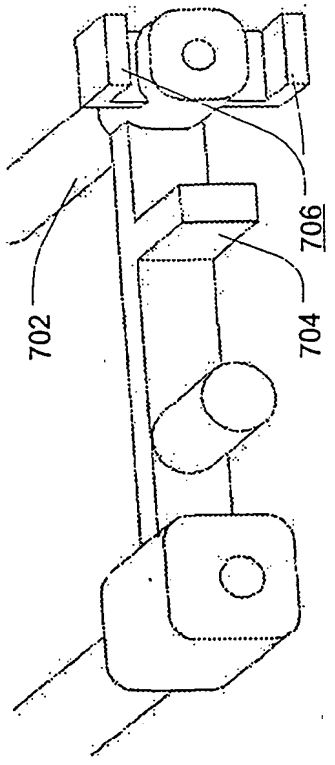

FIG. 7d

FIG. 7

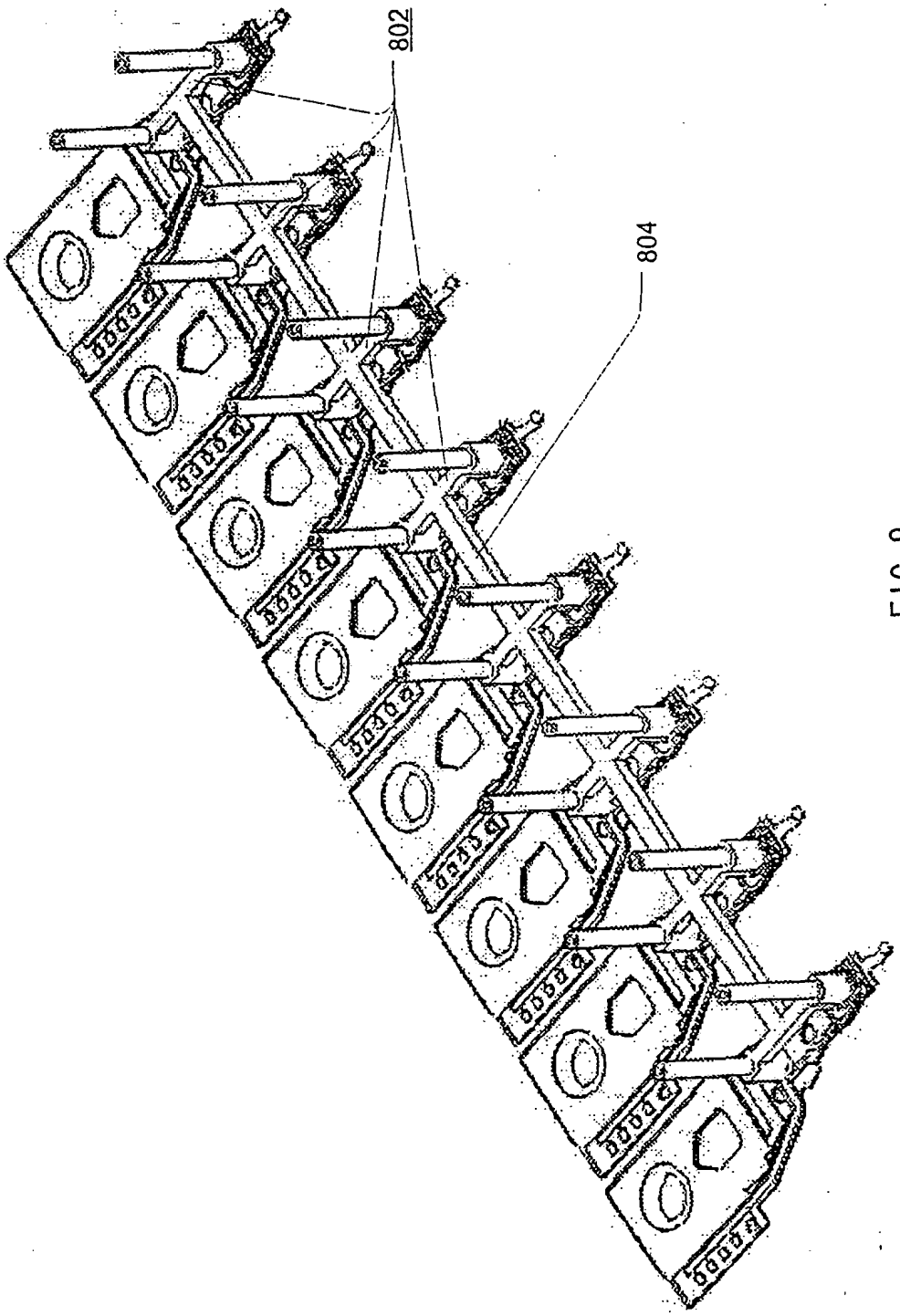

FIG. 8